

# An Efficient Predictor of Renewable Energy Based on Deep Learning Technique (DGBM) and Multi-Objectives Optimization Function

Zainab K. Al-Janabi

Department of Computer Science,  
Faculty of Science for Women (SCIW),  
University of Babylon,  
Babylon, Iraq

Samaher Al-Janabi

Department of Computer Science,  
Faculty of Science for Women (SCIW),  
University of Babylon,  
Babylon, Iraq  
samaher@inet.uobabylon.edu.iq

**Abstract**— This paper produces a predictor called **Zero to Max Energy Predictor Model based on Deep Embedded Intelligence Techniques (ZME-DEI)** to predict Dc-power which is the maximum energy generation from renewable resources that does not cause environmental pollution. ZME-DEI model consists of many stages which flow sequentially in stepwise style; the first stage presents collecting data from sensors of weather and solar plant (i.e., the sensors give a stream of data that contain multi-features). The second stage is preprocessing which contains multi-steps such as (a) Merging between two datasets. (b) Using correlation to the new dataset. (c) Splitting readings into intervals, and deleting duplication intervals. In the third stage, the ZME-DEI model is constructed based on adopting gradient boosting techniques through replacing its kernel (i.e., Decision Tree function) with multi parameters optimization functions. The stage begins with dividing the dataset into two sets using five cross-validation methods, the training dataset is used to construct the ZME-DEI model, while the testing dataset is for evaluating in the final stage. Finally, the fourth ZME-DEI stage is used for evaluation results of the testing dataset based on three measures such as coefficient of determination (R<sup>2</sup>), Root Mean Square Error (RMSE), and Accuracy(A). the results explain the robust of ZME-DEI and reduce the computation complexity while the best results get from the optimization objective function that based on three parameters Irritation, AC-Power and Temperature.

**Keywords:** *Embedded Intelligent, DGBM, Multi-objective functions, Renewable Energy, Solar Energy.*

## I. INTRODUCTION

Many researchers mention about the use of Renewable Energy could reduce premature mortality rate, waste job days, and minimize the total costs for healthcare [1][10][11]. Thus, the changing to RE, economic, reduce air pollution with harmful gases in addition to that could assist to employ a large number of workers.

The energy that is come from Renewable Energy Resources (RER) is changeable (non-dispersible, interrupted, and unreliable) [2][12][32] also the lack of sufficient spaces and extensive experience in this field, in addition to the lack of an extensive feasibility study for the implementation of this technology for electric power generation in Iraq, are the obstacles facing this technology[3][4][13].

Embedded Intelligent System (EI) is a nascent project domain, combining machine learning algorithms such as ("machine learning and neural networks, deep learning, expert systems, fuzzy intelligence, swarm intelligence, self-organizing map and extreme learning") and smart resolution-produce abilities into movable and implanted devices or systems [5][31][32]. IoT is the contraction of appliances, software, sensors, operators, and physical objects are embedded in the wireless sensor network(WSN), vehicles, house devices, and other outputs that aid these objects to transmissions and

data sharing[23][24] 25][26]. IoT is rapidly growing with the recent evolutions in wireless technology and embedded devices, with lower energy Microcontrollers that have been evaluated that are typical for IoT's remotely located in separated areas to bind and operate for the large period that need not repairing [5][6][14]. Many implementations that could take advantage of EI are in independent systems and edge computing.[27] The challenges of edge computing for independent driving systems to have the ability to carry out great computational power to satisfy the energy-efficient field that is responsible for ensuring the safeness systems on independent cars[17][18]. The edge computing systems for independent driving want to own the ability to handle vast data from multi-sensing and safeness systems in existent time[7][11][15].

We mention various challenges that should handle to satisfy efficient EI application in hardware like, the requirements for high Computational processing (it is significant since algorithms for EI become so complicated; cost efficiency(to satisfying the need to cost-effective embedded devices against its low batteries power[28][30]); and scalability to adjust various nets, dimensions and topologies( to solutions detection at EI [19][20][22]. appliances that make the algorithms and techniques able to be achieved inside architectures whose malleable and able to be scale to conform the computational demands and hardware resources whose ready for applicable)[8][11]. Many countries in the world suffer from a clear lack of electricity production, which has led most countries to turn towards producing energy from natural sources or environmentally friendly sources that don't cause the emission of carbon dioxide gas while not causing pollution to the environment[9][33][34]. The problem of producing electrical energy from environmentally friendly sources with high efficiency and low cost is one of the most important challenges in this field"[16][21][22][29]. Therefore; this paper will design an integration model based on the concept of deep embedded intelligent techniques. To determine the Main Rules (Constraints) for each unit that are effective in generating the maximum electrical energy based on the nature of each dataset. Added to that, Zero to Max Energy Predictor Model Based on Deep Embedded Intelligence Techniques (ZME-DEI).

The reminded of this paper is organized as follow: section number one shows the introduction, the second section explains the main tools, the third section explain the main stages related to ZME-DEI, fourth section implementation of (ZME-DEI), section fifth show how ZME-DEI suitable for the increase in the production of electrical power compared to other comparable techniques? The final section presents the main conclusion of that work.

## II. BUILD MAX ENERGY PREDICTOR MODEL BASED ON DEEP EMBEDDED INTELLIGENCE TECHNIQUES (ZME-DEI)

This section shows the main stages of ZME-DEI also In Figure 1 there is illustrated the sequential stages of the ZME-DEI model's block diagram, and algorithm (1) for building it.

The summarization of this research can observe below:

- Collecting the sensor's reading from weather and solar plant.

- Merging between those datasets, after that split the result dataset into training and testing based on five cross-validation concepts.
- ZME-DEI predictor building takes the advantage of multi-objective optimization functions by considering the kernel of gradient boosting techniques.
- Evaluation results of ZME-DEI based on five measures.

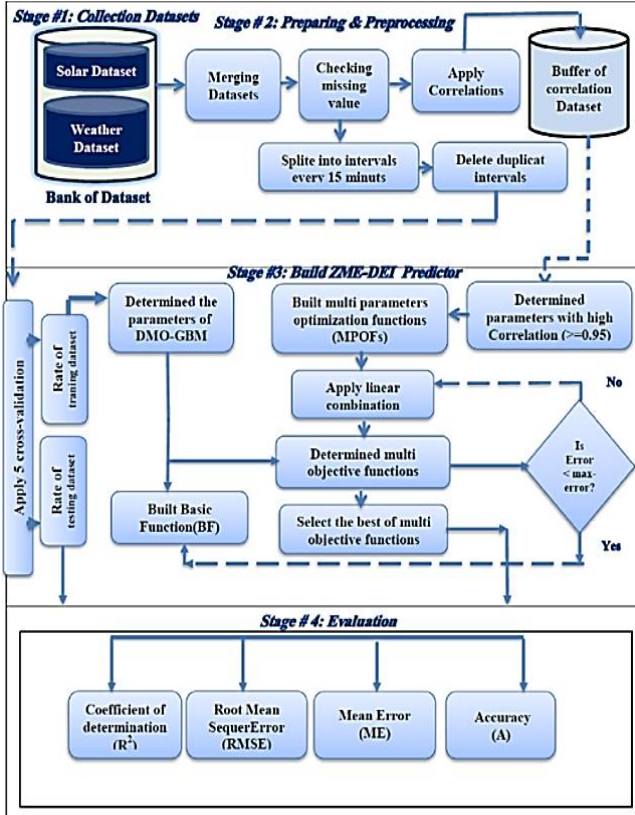


Fig.1 Block diagram of ZME-DEI construction

```

Algorithm#1: ZME-DEI
Input: Plant dataset capture from 7 sensors; Weather dataset capture from 6 sensors
Output: Predict the DC_POWER generation

// Collection data
1: For each dataset, // i=1,2
2:   Call merge dataset //Merge based on Date-Time and Plant-Id
3:   Check missing values
4: End for

// Pre-processing and preparing stage
5: For i=1 to Nr // nr is number of rows in dataset
6:   For j=1 to Nc // nc number of column in dataset
7:     Call correlation
8:     Call Split into intervals
9:   End for
10: End for

// Build ZME_DEI predictor
11: For each id_interval
12:   For i in range(1: total number of records [id_interval])
13:     Split the dataset into Training and Testing through 10-Cross-Validation
14:   End for
15:   For each Training part not used
16:     Call DMO-GBM //predictive value of DC-power
17:   End for
18:   For each Testing part not used
19:     Test stopping conditions //max number of epoch and max error generation
20:     If max error generation <= Emax
21:       GO to step 27
22:     Else
23:       GO to step 15
24:     End If
25:   End for
26: End for

// Evaluation stage
27: Call Evaluation ZME-DEI

```

## A. The ZME-DEI main stages

This section presents four main stages for building an efficient multi objectives optimization model containing the first pre-processing stage which includes multi-steps: collection data, merging between two datasets, checking missing values, and applying the correlation step. Furthermore; we splitting the dataset into multi intervals every 30 minutes based on source key then remove the duplication intervals and take only different intervals to work on it in the next stage. The third stage building ZME-DEI through applying linear combinations to the important features result from the correlation step that affects much on an optimal prediction value of the DC-power.

### 1) Data Pre-processing

This section shows the pre-processing steps as explained in algorithm (2):

- Merging the two datasets by seeking the common features between the solar and weather plants and saving them in one file.
- Checking missing values is applied to drop it with its line.
- Execute the Pearson correlation function to find which parameters or features in the dataset affect much on the DC-power, the coefficient of correlation is used to find out the relationship between target and other features that affect the prediction.
- Finally, splitting data rows into intervals every fifteen minutes, applying compression between similar intervals, and keeping the difference only.

### 2) Building ZME-DEI predictor

This stage takes care of the kernel of the ZME-DEI by taking the advantage of multi parameters optimization functions to determine the number of parameters that optimize the quality of the GBM algorithm.

### 3) Determine the multi parameters optimization functions (MPOFs)

The procedure MPOFs are built to determine the best of multi-objective functions that generate maximum DC-power. Then calling that procedure to be the kernel of DMO-GBM instead of the traditional one. The steps below explain the MPOFs working:

```

Algorithm#2: Preprocessing
Input: Two datasets: solar plant contained features captures from seven sensors; weather dataset contained features captures from six sensors
Output: dataset after preprocessing

// Merging both datasets based on primary key(PLANT_ID, DATE_TIME)
1: Apply features comparison between the datasets
2: Merge both datasets

// Checking missing values
3: For each sample j // j=1..m
4:   For each column k // k=1..n
5:     If k has a missing value
6:       Dropping j at all
7:   End for
8: End for

// Apply correlation
9: For each sample in the dataset
10:   For each column in the dataset
11:     Compute Correlation // RC,S = covr(c,s) / (σcσs) = Exp((c-ē)(s-ē)) / (σcσs)
12:   End for
13: End for

// Split dataset into multi intervals
14: Build empty set called Q
15: For i=1 to the total number of intervals // time of intervals equal 15 minutes
16:   W[i]=read samples
17: End for
18: For i=1 to the total number of intervals
19:   If w[i] = w[i+1]
20:     Delete w[i+1] // delete duplications
21:   Else
22:     Q[i] = w[i]
23:   End if
24: End for
25: End preprocessing

```

Where  $covr(c, s)$  is the covariance between the two variables C and S,  $\sigma_C$  the standard deviation of C,  $\sigma_S$  the standard deviation of S,

$\bar{c}$  the average of C,  $\bar{s}$  the average of S, and Exp the expectation values.

- Find the parameters that have a correlation value with the target much or equal to 0.95 in the dataset.
- Apply linear combination for those parameters from the parameters with high correlation to the parameters with the least correlation such as the equation below.
$$\sum_{i=1}^n \text{Fheigh Cor}_1 \dots \text{FleashtCor}_n \dots (1)$$
- Determine the significant parameters such as (Ac, Irradiation, and Temperature) that affect the prediction.
- Apply the multi-objective functions (maximum value) to the first two parameters, then to the second two parameters, and so on until combine the three parameters are in one function.
- Find the best multi-objective functions from the four functions.
- Set these functions as kernel of the DMO-GBM algorithm.

The steps below building a procedure of multi parameters optimization functions (MPOFs).

```

Procedure Multi Parameters Optimization Functions(MPOFs)
1: For i=1 to Nr // nr is number of rows in dataset
2:   For j=1 to Nc // nc number of column in dataset
3:     If correlation-value-target with j >= 0.95 then
4:       X= a[i,j]
5:       Zk= Linear combination X // Zk is MPOFs become as new kernel of DGBM
6:       //Multi-objective functions of two parameters (Ac & Irr)
7:       For i=1 to Nr
8:         MoF1= max(Ac[i] + Irr[i])
9:       End for
10:      Return MoF1
11:      //Multi-objective functions of two parameters (Ac & Tem)
12:      For i=1 to Nr
13:        MoF2= max(Ac[i] + Tem[i])
14:      End for
15:      Return MoF2
16:      //Multi-objective functions of two parameters (Tem & Irr)
17:      For i=1 to Nr
18:        MoF3= max(Irr[i] + Tem[i])
19:      End for
20:      Return MoF3
21:      //Multi-objective functions of three parameters (Tem, AC & Irr)
22:      For i=1 to Nr
23:        MoF4= max(AC[i] + Irr[i]+ Tem[i])
24:      End for
25:      Return MoF4
26:    End if
27:  End for
28: End for
29: End MPOFs

```

Where X is a variable that contains an array a[i,j] of the dataset, Z<sub>k</sub> is a linear combination of a multi parameters objective functions (MPOFs).

### B. Develop GBM (DMO-GBM)

In this section; using the training intervals to build models after replace the kernel of GBM by DMO. The algorithm (3) shows the steps of DMO-GBM.

```

Algorithm #3: DMO-GBM
Input: D: dataset after preprocessing
Output: Optimal of DC-power
Initialization: Tr: training data, Fx: array for predicted values of Tr, rc: rows counter,
CDMO-GBM: counter of develop GBM, DMO-GBM_MAX: max number of
DGBM, Org_target: array for original target of Tr, y: index of
target, N: # data records in D.

1: For i=1 to total # sample in Tr
// Find the initial prediction for all data records in Tr by:
2:   Calculate mean of target values Mean (Dc-power)
3:   While rc < N
4:     Fx[0,rc] = Mean(Dc-power)
5:     Org_target[rc] = Tr[y,rc]
6:     Increase row counter: rc = rc + 1
7:   End while
8:   Call MPOFs
9:   While CDMO-GBM <= DMO-GBM_MAX, build optimization model by:
10:    rc = 0
11:    While rc < N, Update target values of Tr by:
12:      Residual [rc] = Org_target [rc] - Fx[CDMO-GBM-1, MPOFs, rc]
13:      Tr[y,rc] = Residual [rc]
14:      Increase rows counter: rc = rc + 1
15:    End while
16:    For each multi parameters optimization function in DMO-GBM:
17:      While rc_DMO-GBM < # rows in DMO-GBM, update prediction values by:
18:        Fx[CDMO-GBM-1, MPOFs, rc]=
          Fx[CDMO-GBM-1, MPOFs, rc]+ (Sk * DMO-
          GBM.predictaed_valus)
19:        Increase counter of data rows in final DMO-GBM:
          rc_DMO-GBM = rc_DMO-GBM + 1
20:      End while
21:    End for
22:  End while
23: End for
24: Return DMO-GBM model with array of prediction values Fx.
25: // Build the testing stages of DMO-GBM model.
End DMO-GBM

```

Where DMO-GBM\_MAX is a maximum development of multi-objective gradient boosting machine.

## III. IMPLEMENTATION OF ZME-DEI

This section will present the main result extracted from each stage of ZME-DEI to predict DC-power which is the maximum energy generation from renewable resources that does not cause environmental degradation.

ZME-DEI model shows many activities which flow sequentially in stepwise style; stage one shows real-time collecting data from two datasets weather and solar plant each having basic features then checking if the dataset contains missing values for dropping.

Stage two pre-processing contains: (a) Merging between two datasets. (b) Using correlation to the final dataset. (c) Splitting readings into intervals every fifteen minutes. (e) Delete duplication intervals. In the third stage, ZME-DEI model is constructed based on gradient boosting techniques.

The final stage includes evaluation results based on three measures such as coefficient of determination (R<sup>2</sup>), Root Mean Square Error (RMSE), Mean Error (ME), and Accuracy(A).

### A. Collecting datasets

In this stage, the datasets collected through 5 months are used to build and test the proposed model. These data or sensors readings were taken from two plants for generating electric power. We must point to the limitations related to the collection readings like energy consumption of sensors battery which is the main cause of unreasonable readings. Tables I and II show the sample of weather and solar plant consequently.

TABLE I. SAMPLE OF WEATHER DATASET

IRR	MODULE_TEM	AMBIENT_TEM	SOU_K	P_ID	D_T
0.00086 2721	23.096691 93	24.2892111 3	HmiyD2TTL FNqkNe	4135 001	15/05/2020 05:45
0.00588 6957	22.206756 6	24.0884460 7	HmiyD2TTL FNqkNe	4135 001	15/05/2020 06:00

0.02228 1607	22.353458 67	24.0116352 7	HmiyD2TTL FNqkNe	4135 001	15/05/2020 06:15
0.04940 9724	22.893282	23.9767312 7	HmiyD2TTL FNqkNe	4135 001	15/05/2020 06:30
0.09539 4454	24.442443 93	24.21899	HmiyD2TTL FNqkNe	4135 001	15/05/2020 06:45
0.14194 0443	27.185652 87	24.5373984	HmiyD2TTL FNqkNe	4135 001	15/05/2020 07:00
0.15471 2676	28.888477 86	24.8159595	HmiyD2TTL FNqkNe	4135 001	15/05/2020 07:15
0.14879 9153	29.605643 8	24.9887898 7	HmiyD2TTL FNqkNe	4135 001	15/05/2020 07:30
0.00086 2721	23.096691 93	24.2892111 3	HmiyD2TTL FNqkNe	4135 001	15/05/2020 05:45
0.00588 6957	22.206756 6	24.0884460 7	HmiyD2TTL FNqkNe	4135 001	15/05/2020 06:00

TABLE II. SAMPLE OF SOLAR DATASET

T_YIE LD	D_YIE LD	AC_ P	DC_ P	SOU_K	P_ID	D_T
6987759	0	0	0	3PZuoBAID5Wc2 HD	41350 01	15/05/2020 0 :15
7602960	0	0	0	7JYdWkrLSPkdwr 4	41350 01	15/05/2020 0 :15
7158964	0	0	0	McdE0feGgRqW7 Ca	41350 01	15/05/2020 0 :15
7206408	0	0	0	VHMLBKOkgfrU VDU	41350 01	15/05/2020 0 :15
7028673	0	0	0	WRmjgnKYAwPK WDb	41350 01	15/05/2020 0 :15
6522172	0	0	0	ZnxXZZZa8U1GX gE	41350 01	15/05/2020 0 :15
7098099	0	0	0	ZoEaEvLYb1n2sO q	41350 01	15/05/2020 0 :15
6271355	0	0	0	adLQvID726eNBS B	41350 01	15/05/2020 0 :15
6987759	0	0	0	3PZuoBAID5Wc2 HD	41350 01	15/05/2020 0 :15
7602960	0	0	0	7JYdWkrLSPkdwr 4	41350 01	15/05/2020 0 :15

B. Pre-Processing

This stage involved many steps to handle problems related to the dataset to extract useful information and get thesis' target quickly as to show this later.

▪ Step #1: Merging

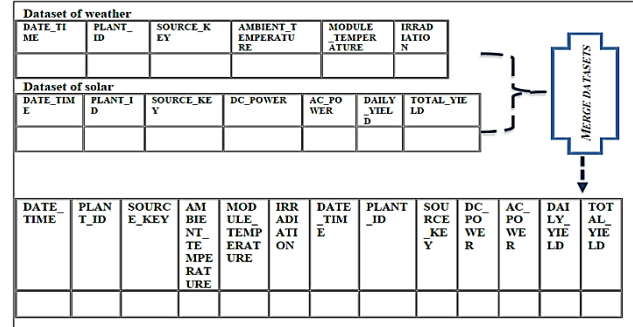
To apply merging between two datasets based on D\_T and P\_ID features we need firstly adjust the D\_T format to each dataset from the (day, month, year, hour, and minutes) formatting (i.e, %d-%m-%Y %H:%M) to the (year, month, day, hour, minutes, second)

formatting (i.e, %Y-%m-%d %H:%M:%S) to make standard formatting in the python programming language. Drop unnecessary features and apply merging through the D\_T feature.

Table III shows the results of the step merging that are used to join the original datasets within one dataset along the column and rows.

The main purpose of the merging step is to fill gaps in data, increase the samples size, and improve the robustness of results.

TABLE III. THE MERGING OF WEATHER AND SOLAR DATASETS



▪ Step #2 checking missing values in the dataset

Search for the missing value is applied to drop it with its row because the dataset that dealing with contains a stream of data therefore deleting one or more rows does not affect the prediction over a long time. In general, we found that dataset don't contain missing values. The main purpose of this step is to avoid training failing and make the prediction more accurate.

▪ Step #3 The Correlations between Parameters in the Dataset

The correlation coefficient is a statistical measure of how closely two or more variables are related to one another. As a results when applying the correlation found high correlation among (DC-power, AC, IRR, and MODULE\_TEM) reach to high of 0.95. Table IV show that the correlation between the target and AC is equal to 1.0 meaning there is a perfect correlation between them, while the correlation with MODULE\_TEM is equal to 0.947 and with IRR is equal to 0.98 that satisfy the condition in the MPOFs procedure. The main purpose of correlation is to reduce the training computations and as a result, reduce the time and space complexity .

TABLE IV. THE CORRELATION COEFFICIENT AMONG THE 7 PARAMETERS (SENSORS READINGS)

	DC_P	AC_P	D_YIELD	T_YIELD	AMBIENT_TEM	MODULE_TEM	IRR
DC_P	1.000	1.000	0.096	0.008	0.710	0.947	0.984
AC_P	1.000	1.000	0.096	0.008	0.710	0.947	0.984
D_YIELD	0.096	0.096	1.000	0.020	0.463	0.200	0.085
T_YIELD	0.008	0.008	0.020	1.000	-0.033	-0.013	-0.003
AMBIENT_TEM	0.710	0.710	0.463	-0.033	1.000	0.852	0.719
MODULE_TEM	0.947	0.947	0.200	-0.013	0.852	1.000	0.960
IRR	0.984	0.984	0.085	-0.003	0.719	0.960	1.000

▪ Step #4 Split Dataset into multi intervals

Splitting data rows into fifty intervals every fifteen minutes, applying compression between similar intervals, and keeping the difference only.

Table V. Split Dataset into Intervals

Pre.	# Points related to Pre.	Pre.	# Points related to Pre.
Per #1	3202	Per #26	415
Per #2	3067	Per #27	414
Per #3	3010	Per #28	401
Per #4	3007	Per #29	350
Per #5	2996	Per #30	326
Per #6	2996	Per #31	324
Per #7	2978	Per #32	321
Per #8	2961	Per #33	320
Per #9	2950	Per #34	318
Per #10	2939	Per #35	307

Per #11	2913	Per #36	297
Per #12	2895	Per #37	285
Per #13	2825	Per #38	279
Per #14	2806	Per #39	262
Per #15	2771	Per #40	252
Per #16	2754	Per #41	249
Per #17	2751	Per #42	246
Per #18	2699	Per #43	239
Per #19	2643	Per #44	235
Per #20	2637	Per #45	233
Per #21	2598	Per #46	232
Per #22	2523	Per #47	193
Per #23	648	Per #48	190
Per #24	476	Per #49	188
Per #25	417	Per #50	150

C. Where Per is an interval or period related to fifteen minutes.

Table VI. the Result of Training dataset in DGBM

Training	Testing	MOF1=AC+IRR	MOF2=AC+TEM	MOF3=TEM+IRR	MOF4=AC+IRR+TEM
80%	20%	232.600	259.883	28.683	309.332
60%	40%	220.120	250.910	23.710	254.322
50%	50%	202.150	200.783	20.503	172.232
40%	60%	195.436	220.232	15.323	189.214
20%	80%	231.200	233.853	19.236	211.203

Table VII. the Result of Testing dataset in DGBM

Training	Testing	MOF1=AC+IRR	MOF2=AC+TEM	MOF3=TEM+IRR	MOF4=AC+IRR+TEM
80%	20%	229.467	254.403	22.661	254.452
60%	40%	118.419	138.912	15.852	109.123
50%	50%	110.987	130.952	14.202	100.325
40%	60%	192.257	220.694	12.235	251.773
20%	80%	232.600	123.213	11.235	233.452

Table XI: Results of Evaluation Measures for Training and Testing Datasets

RATE OF TRAINING DATASET	RATE OF TESTING DATASET	RESULTS OF THE TRAINING DATASET			RESULTS OF THE TESTING DATASET		
		R2	RMSE	ACCURACY	R2	RMSE	ACCURACY
80%=40 INTERVALS	20%=10 INTERVALS	0.423	0.497	0.945	0.167	0.328	0.883
60%=30 INTERVALS	40%=20 INTERVALS	0.0562	0.526	0.853	0.433	0.334	0.741
50%=25 INTERVALS	50%=25 INTERVALS	0.301	0.792	0.870	0.010	0.421	0.800
40%=20 INTERVALS	60%=30 INTERVALS	0.296	0.787	0.891	0.020	0.203	0.825
20%=10 INTERVALS	80%=40 INTERVALS	0.097	0.0167	0.765	0.136	0.190	0.631

#### IV. DISUSSION

This paper produces a predictor named Zero to Max Energy Predictor Model based on Deep Embedded Intelligence Techniques (ZME- DEI) to predict DC-power which is the maximum energy generation from renewable resources that does not cause environmental degradation. ZME- DEI model shows many stages: Collecting the sensor's reading from weather and solar plant, merging between those datasets, after that split the result dataset into training and testing based on five cross-validation concepts, ZME-DEI predictor building take the advantage of multi-objective optimization functions by considering the kernel of gradient boosting techniques to obtain this goal. Evaluation results of ZME-DEI based on five measures.

A. *How is the proposed optimization model suitable for the increase in the production of electrical power compared to other such comparable techniques?*

The proposed model relied on the substitution of the core for one of the best prediction techniques represented by the gradient boosting machine by a multi-objective function in which the transactions that affect the generation of electric power (DC-power) were relied upon by merging between the best prediction technique and the multi-objective optimization function and then obtaining prediction results with high accuracy depending on different accuracy scales were taken into account.

B. *Can the polynomial optimization function improve the performance of the prediction network represented by the gradient boosting algorithm?*

Yes, the polynomial optimization function was able to improve the performance of the gradient boosting algorithm because it took

into account only the most influential factors in power generation. In addition, it was able to avoid the problems in the algorithm, which is to determine the number of decision trees, the depth of each tree, and the long time of training it.

C. *What are the factors affecting the generation of DC-power?*

by calculating the correlation between the values obtained from the sensors, it was found that irradiation, alternating current(ac), and temperature are the most influential factors in generating dc-power.

D. *Do natural factors affect the generation of DC-power?*

Yes, by defining the knowledge constraints, it was found that dust harms the efficiency of the solar cell in generating the largest possible energy, as well as the appropriate place or area to install these panels in terms of a large and open area to absorb the largest amount of solar energy.

#### V. CONCLUSIONS

This section explains the main conclusions found through implementing the suggested system (ZME-DEI). Where we focus on the point of how the proposed model handles the challenges shown in the previous sections ( i.e., programming and application challenges. Also will suggest a set of recommendations that can work on it by other researchers in the future.

In general; we can summarize the main conclusions found from implementing this study:

Although Renewable Energy is considered one of the main resources for generating energy and it is characterized by multi-features that make it a prismatic resource to cover the need of humans for energy but on the other side, it required more effort from humans to get it.

The main challenges of IoT are collecting the data from multi-sensors that performance of it based on the life cycle of the battery. When the battery lost energy then this leads to a loss of some value or gives uncertainty values, therefore the (ZME-DEI) solves this problem by dropping any missing values.

Sometimes the data collected from multi-sensors suffer from duplications of their records, therefore, this leads to an increase in the computations. In general; the (ZME-DEI) handles this problem through split the dataset into multi-intervals, each interval represents a stream of data taken through 30 minutes. Then create a buffer to save only the different intervals to work on it in the next step.

Integration data always leads to an increase in the accuracy of results and make it more understood by users. Therefore, this work activates this feature through integrated weather and solar datasets to get more accurate results.

The GBM is one of the primitive tools for prediction based on Decision Tree results, but on the other side, it is required to determine multi-parameters such as root, number of nodes, and depth of the tree. This work handles the limitations of GBM by replacing the kernel (DT) with a mathematical function based on linear combinations. This leads to getting high accuracy results in a short implementation time. In general, the best results get through using multi-objective functions that have parameters.

The (ZME-DEI) gives the best results when splitting the different intervals through a rate of 80% of the interval to training while 20% of intervals to testing and using MOF4 as kernel of GBM this make the accuracy of the model equal to 95%.

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