

**Example (1):**

Evaluate the commutator  $\left[x, \frac{d}{dx}\right]$ , applying the commutator on an arbitrary function  $f(x)$

**Solution:**

$$\begin{aligned} \left[x, \frac{d}{dx}\right] F(x) &= x \frac{d}{dx} f(x) - \frac{d}{dx} (x f(x)) \\ &= x \frac{df(x)}{dx} - x \frac{df(x)}{dx} - f(x) = -f(x) \end{aligned}$$

وبحذف  $f$  من الطرفين نحصل على

$$\left[x, \frac{d}{dx}\right] F(x) = -f(x)$$

$$\left[x, \frac{d}{dx}\right] = -1$$

From the Angular momentum  $L$  of a particle having linear momentum  $p$  is:

$$L = r \times P$$

$$\therefore L = r \times P = \begin{vmatrix} i & j & k \\ x & y & z \\ p_x & p_y & p_z \end{vmatrix}$$

$$L = i(y p_z - z p_y) + j(z p_x - x p_z) + k(x p_y - y p_x)$$

$$\therefore L_x = y p_z - z p_y = -i\hbar \left( y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y} \right)$$

$$\therefore L_y = z p_x - x p_z = -i\hbar \left( z \frac{\partial}{\partial x} - x \frac{\partial}{\partial z} \right)$$

$$\therefore L_z = x p_y - y p_x = -i\hbar \left( x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} \right)$$

**Example (2):**

Prove that the commutator  $[x, p_x] = i\hbar$

**Solution:**

$$[x, p_x] \Psi_{(x)} = (x p_x - p_x x) \Psi_{(x)} = (-i\hbar x \frac{\partial}{\partial x} + i\hbar \frac{\partial}{\partial x} x) \Psi_{(x)}$$

$$[x, p_x] \Psi_{(x)} = i\hbar \left\{ -x \frac{\partial \Psi_{(x)}}{\partial x} + \frac{\partial}{\partial x} (x \Psi_{(x)}) \right\}$$

$$[x, p_x] \Psi_{(x)} = i\hbar \left\{ -x \frac{\partial \Psi_{(x)}}{\partial x} + x \frac{\partial \Psi_{(x)}}{\partial x} + \Psi_{(x)} \frac{\partial x}{\partial x} \right\}$$

$$[x, p_x] \Psi_{(x)} = i\hbar \Psi_{(x)}$$

$$\therefore [x, p_x] = i\hbar$$

Similarly we can prove that

$$[y, p_y] = [z, p_z] = i\hbar$$

$$\therefore [x, p_x] = [y, p_y] = [z, p_z] = i\hbar$$

And

$$[p_x, x] = [p_y, y] = [p_z, z] = -i\hbar$$

**Example (3):**

Prove that  $[x, p_y] = 0$

**Solution:**

$$[x, p_y] \Psi_{(x)} = (x p_y - y p_x) \Psi_{(x)} = (-i\hbar x \frac{\partial}{\partial y} + i\hbar \frac{\partial}{\partial y} x) \Psi_{(x)}$$

$$[x, p_y] \Psi_{(x)} = i\hbar \left\{ -x \frac{\partial \Psi_{(x)}}{\partial y} + \frac{\partial}{\partial y} (x \Psi_{(x)}) \right\}$$

$$[x, p_y] \Psi_{(x)} = i\hbar \left\{ -x \frac{\partial \Psi_{(x)}}{\partial y} + x \frac{\partial \Psi_{(x)}}{\partial y} + \Psi_{(x)} \frac{\partial x}{\partial y} \right\} = 0$$

$$[x, p_y] \Psi_{(x)} = 0$$

$$\therefore [x, p_y] = 0$$

Similarly we can prove that:

$$[x, p_z] = [y, p_x] = [y, p_z] = [z, p_x] = [z, p_y] = 0$$

#### Example (4):

For angular momentum operator L, show that  $[L_x, L_y] = i\hbar L_z$

#### Solution:

$$[L_x, L_y] = [(y p_z - z p_y), (z p_x - x p_z)]$$

$$[L_x, L_y] = [y p_z, z p_x] - [y p_z, x p_z] - [z p_y, z p_x] + [z p_y, x p_z]$$

$$[L_x, L_y] = y p_x [p_z, z] - y p_z [p_z, x] - z p_x [p_y, z] + x p_y [z, p_z]$$

$$[L_x, L_y] = y p_x [p_z, z] + x p_y [z, p_z]$$

$$\text{But } [p_z, z] = -i\hbar, \text{ and } [z, p_z] = i\hbar$$

Therefor

$$[L_x, L_y] = y p_x (-i\hbar) + x p_y (i\hbar) = i\hbar x p_y - i\hbar y p_x$$

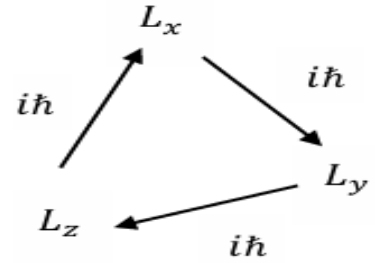
$$[L_x, L_y] = i\hbar (x p_y - y p_x)$$

$$[L_x, L_y] = i\hbar L_z$$

Similarly we can prove that

$$[L_y, L_z] = i\hbar L_x$$

$$[L_z, L_x] = i\hbar L_y$$



### Example (5):

Evaluate the commutator:

$[x^2, \frac{d}{dx}]$  applying the commutator on an arbitrary function  $f(x)$ .

**Solution:**

$$[x^2, \frac{d}{dx}] f(x) = x^2 \frac{d}{dx} f(x) - \frac{d}{dx} (x^2 f(x))$$

$$\frac{d}{dx} (x^2 f(x)) = 2x f(x) + x^2 \frac{df(x)}{dx}$$

So:

$$x^2 \frac{d}{dx} f(x) - (2x f(x) + x^2 \frac{df(x)}{dx})$$

$$= -2x f(x)$$

$$\therefore \left[ x^2, \frac{d}{dx} \right] = -2x$$